



KONGSBERG

INSTRUCTION MANUAL

cNODE Mini MF 4000 m





KONGSBERG

cNODE Mini
Medium Frequency, 4000 m
Instruction manual

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Table of contents

ABOUT THIS MANUAL	5
CNODE MINI.....	6
System description	7
Naming description	7
System diagram.....	8
System units	9
Scope of supply.....	11
General supply conditions.....	12
Receipt, unpacking and storage.....	12
Equipment responsibility.....	12
Support information	13
CABLE LAYOUT AND INTERCONNECTIONS.....	14
End cap connectors	15
Power converter connectors	16
OPERATIONAL PROCEDURES	18
Charging the transponder	19
Powering up the transponder	20
Powering down the transponder.....	21
Responder function	21
Setting up the internal tilt sensor	22
Configuring the transponder	22
MAINTENANCE	23
Charging the transponder	24
Cleaning the transponder	25
Inserting an O-ring.....	25
Opening the transponder	26
Changing the transducer	26
Lubricating the subsea connector.....	27
SPARE PARTS	28
cNODE Mini maintenance kit spare part.....	29
TD40V spare part.....	29
TD180 spare part.....	29
TD80V spare part.....	30
Split transponder (S) for remote transducer spare part	30
Remote transducer TDR180 spare part.....	30
Remote transducer TDR40V spare part.....	30

Remote transducer TDR30H spare part.....	31
Remote transducer TDR30V spare part.....	31
Transducer cable 6 m spare part	31
Depth sensor spare part.....	31
Battery spare part	32
Tube spare part.....	32
End cap spare part.....	32
Battery charger spare part	32
Power supply spare part.....	33
EMI Shield gasket - spare part.....	33
Retainer cord - Spare part	33
Transponder Test and Configuration unit (TTC30) spare part.....	33
TECHNICAL SPECIFICATIONS.....	34
Performance specification.....	35
Weight and outline dimensions	37
Power specifications.....	39
Environmental specifications	40
DRAWING FILE.....	41
cNODE Mini 31-40V-St outline dimensions.....	42
cNODE Mini 34-180 outline dimensions	43
cNODE Mini 34-40V outline dimensions	44
cNODE Mini 3x-180-D outline dimensions	45
cNODE Mini 3x-80V-D-St outline dimensions	46
cNODE Mini 31-80V-St outline dimensions.....	47

About this manual

Observe this general information about the cNODE Mini Instruction manual; its purpose and target audience.

Purpose of manual

The purpose of this instruction manual is to provide the descriptions and procedures required to install, operate and maintain the cNODE Mini.

Target audience

The manual is intended for all users of cNODE Mini.

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cNODE Mini

Topics

[System description, page 7](#)

[Naming description, page 7](#)

[System diagram, page 8](#)

[System units, page 9](#)

[Scope of supply, page 11](#)

[General supply conditions, page 12](#)

[Support information, page 13](#)

System description

cNODE Mini is a family of transponders for underwater positioning and data links. cNODE Mini is designed to be a very versatile system with many interchangeable parts.

The transponders are operated from Acoustic Position Operator Station (APOS) with an acoustic telemetry link for command and data transfer. The transponders are compatible with both HiPAP Cymbal acoustic protocol for positioning and data link, and HPR 400 channels and telemetry. Perform SSBL positioning with a total of 560 HiPAP Cymbal channels and 56 HPR 400 channels, LBL positioning and acoustic link for command and data transfer. The transponders have both transponder and responder functions.

The transponders are rated to up to 4000 m with a housing made of aluminium or stainless steel. The transponders are designed with a modular construction which means that the transponder electronics, battery pack and optional add-on's can be replaced individually to suit the operation.

A transponder is normally a self-contained unit, receiving power from an internal rechargeable battery pack. The transponder can also be powered from an external power supply.

The transponder unit is designed with a modular construction such that the transponder electronics, battery pack and options (where applicable) can be replaced individually.

The transponder may be secured to a subsea structure using mounting brackets.

Note

Always make sure the vent screw is closed before deployment.

Naming description

The transponder name consists of the model name, the model number, the transducer beam width and any options included.

Model name

Mini

Model number

The two digit number in the transponder name describes the frequency band and the depth rating.

Example:

First number =Frequency band	Second number = Depth rating
3 = 30 kHz	4 = 4000 meters

Transducer beam width

180 = 180° beam width

40V = 40° vertical beam width

80V = 80° vertical beam width

Optional transponder modules

D: Depth sensor

Example of transponder name

The transponder name cNODE Mini 34-40V indicates that this transponder unit is operating in the 30 kHz, rated to 4000 metres depth, with a 40° transducer beam width vertical. The standard transponder tube material is aluminium.

Transponder identification

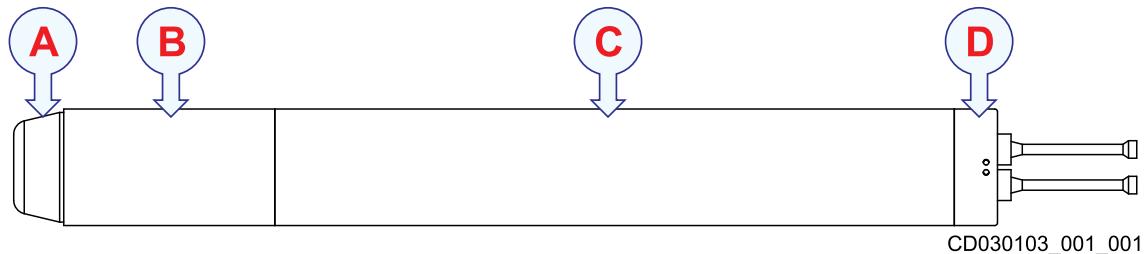
The transponders have labels that identifies:

- the transponder name
- serial number
- default channels

System diagram

The system diagram identifies the main components of the cNODE Mini.

cNODE Mini



- A** Transducer
- B** Top section module
- C** Tube
- D** End cap module

System units

cNODE is a family of transponders for underwater positioning and data links. The cNODE Mini is designed to be a very versatile system with many interchangeable units.

TD180

The transducer has a 180° omnidirectional beam width, and is available in aluminium and stainless steel.



TD40V

The transducer has a 40° vertical beam width, and is available in aluminium and stainless steel.



TD80V

The transducer has a 80° vertical beam width, and is only available in stainless steel.



Split transponder for remote transducer (S)

This top end cap has a standard external connector for remote transducers.



TDR180

The transducer has a 180° omnidirectional beam width. Available in aluminium and Super Duplex stainless steel.



TDR40V

The transducer has a 40° vertical beam width. Available in aluminium and Super Duplex stainless steel.



TDR30H

The transducer has a 30° horizontal beam width. Available in aluminium and Super Duplex stainless steel.



TDR30V

The transducer has a 30° vertical beam width. Available in aluminium and Super Duplex stainless steel.



Transducer cable 6 m

The transducer cable has two Subconn connectors; MCIL4F and MCIL4M. The cable connects all the remote transducers to the transponder.



Depth sensor

The depth sensor is a top section module. Available in aluminium and stainless steel.



Tube

The tube contains the battery and the electronics for the Mini transponder. Available in aluminium and stainless steel.



End cap

The end cap has a vent screw, safety valve with on/off switch and two external connectors and is available in aluminium and stainless steel.



Battery

The battery is a rechargeable nickel-metal hybrid battery.



Battery charger

Charging the battery has some risks, read the procedure first.



Power supply

Use the AC to DC converter for continuous charging of the cNODE Mini from an AC source.



Available in aluminium and stainless steel.

TTC (Transponder Test and Configuration unit)

The TTC 30 unit is for on deck testing and configuration of medium frequency transponders. It can test all KONGSBERG transponder channels, Cymbal and HPR 400. It can also test telemetry transponders with internal and external sensors.



Scope of supply

The following items are provided when you order a transponder.

- Transponder
- Instruction manual

General supply conditions

The following general supply conditions apply to this Kongsberg cNODE Mini delivery.

Receipt, unpacking and storage

Upon accepting shipment of the equipment, the shipyard and/or the dealer must ensure that the delivery is complete and inspect each shipping container for evidence of physical damage.

If the inspection reveals any indication of crushing, dropping, immersion in water or any other form of damage, the recipient should request that a representative from the company used to transport the equipment be present during unpacking.

All equipment must be inspected for physical damage, i.e. broken controls and indicators, dents, scratches etc. during unpacking. If any damage to the equipment is discovered, the recipient must notify both the transportation company and Kongsberg Maritime so that Kongsberg Maritime can arrange for replacement or repair of the damaged equipment.

Once unpacked, the equipment must be stored in a controlled environment with an atmosphere free of corrosive agents, excessive humidity or temperature extremes.

The equipment must be covered to protect it from dust and other forms of contamination when stored.

Equipment responsibility

Unless otherwise stated in the contract, the shipyard doing the installation and/or equipment dealer becomes fully responsible for the equipment upon receipt.

The duration of responsibility cover:

- The period of time the equipment is stored locally before installation
- The entire installation process
- Commissioning
- The period of time between commissioning and the final acceptance of the equipment by the end user or owner

Unless other arrangements have been made in the contract, the Kongsberg cNODE Mini guarantee period (as specified in the contract) begins when the acceptance documents have been signed.

Support information

If you need support for your Kongsberg cNODE Mini you must contact Kongsberg Maritime AS.

- **Company name:** Kongsberg Maritime AS
- **Address:** Strandpromenaden 50, 3190 Horten, Norway
- **Telephone, 24h support:** +47 33 03 24 07
- **Telefax:** +47 33 04 76 19
- **Website:** <http://www.km.kongsberg.com>
- **Support website:** http://www.km.kongsberg.com/support_hpr
- **E-mail address:** km.support.hpr@kongsberg.com

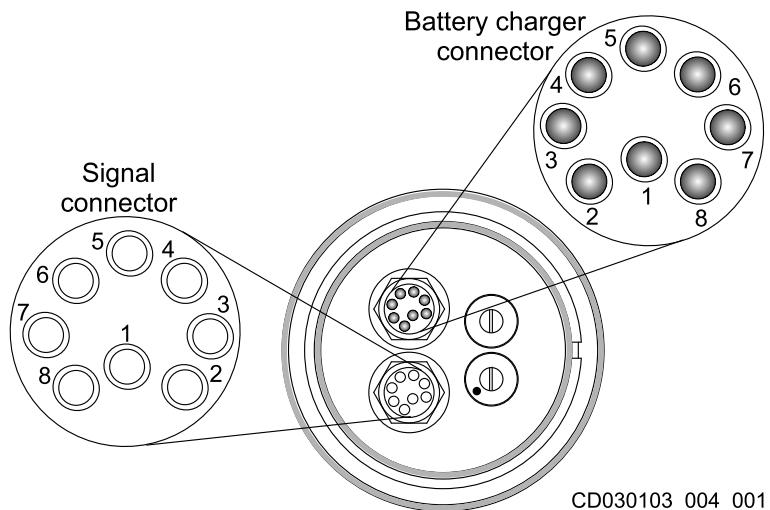
Cable layout and interconnections

Topics

[End cap connectors, page 15](#)

[Power converter connectors, page 16](#)

End cap connectors



The end cap has two connectors:

- External signal connector; 8 pin male subconn MCBH8M for serial line, external power supply and responder signal
- External charge connector; 8 pin female subconn MCBH8F for charging the battery

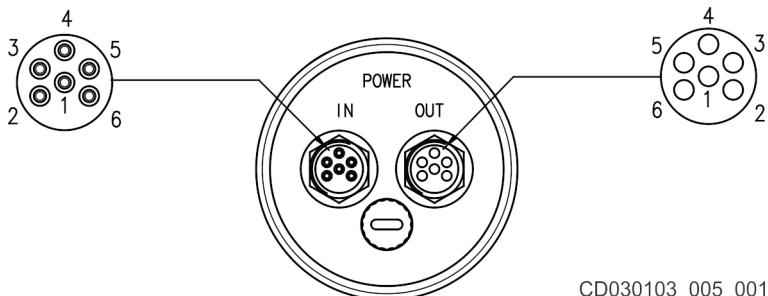
Signal connector pin out

Pin no.	Signal
1	TP TX
2	GND
3	TP RX
4	Responder +
5	Responder —
6	GND
7	Ext. power +15 VDC (use in parallel with 8)
8	Ext. power +15 VDC (use in parallel with 7)

Battery charger connector pin out

Pin no.	Signal
1	Charger A
2	Charger B
3	Charger C
4	NTC A
5	NTC B
6	NTC C
7	GND
8	GND

Power converter connectors



The end cap has two connectors:

- Power in connector; 6 pin male subconn MCBH6MAS
- Power out connector; 6 pin female subconn MCBH6FAS

Power in connector pin out

Pin no.	Signal
1	Responder +
2	115/230 VAC (L)
3	115/230 VAC (L)
4	Responder -
5	115/230 VAC (N)
6	115/230 VAC (N)

Power out connector pin out

Pin no.	Signal
1	Responder +
2	15 VDC
3	15 VDC
4	Responder -
5	GND
6	GND

Operational procedures

Topics

- [Charging the transponder, page 19](#)
- [Powering up the transponder, page 20](#)
- [Powering down the transponder, page 21](#)
- [Responder function, page 21](#)
- [Setting up the internal tilt sensor, page 22](#)
- [Configuring the transponder, page 22](#)

Charging the transponder

The battery is charged inside the cNODE Mini. This is connected with some risk, please read the information below and follow the charge procedure carefully.

Prerequisites

Caution

When you are charging the battery ensure good ventilation and stable temperature. Do not cover the transponder. No open fire, sparks or smoking in the area.

NiMH batteries can generate some hydrogen and oxygen gas, the amount depending on certain conditions. Most often this generation occurs during charging.

Procedure

- 1 Switch off the transponder.
- 2 Climatize the transponder.

The battery must have a temperature between 5 °C and 40 °C. Recommended charging temperature is 25 °C.

- 3 Unscrew the vent screw until you feel some resistance (a nylon washer is forced against a metal surface). The O-ring is now visible.

Hold the transponder in an upright position while you do this, so that any water droplets caught around the vent screw comes out, rather than going inside the cNODE Mini.

- 4 Connect the charger plug to the connector on the transponder marked CHARGE.
- 5 Connect Power supply to mains (110 or 220 VAC).

- 6 Switch on the charger.

The charger measures the battery status; all LEDs emit constant yellow light. If the temperature is out of range, the LEDs will flash orange/green.

Fast charge starts and the LEDs emit constant orange light.

When the battery is fully charged the LEDs will be green with a yellow flash every minute.

- 7 Switch off the charger.

- 8 Disconnect the charger plug from the transponder.

- 9 Close the vent screw.

Tighten the vent screw by hand only, until you feel a rather sudden resistance. (an internal axial O-ring hits a metal surface, compresses 0.3 mm, before 2 metal surfaces meet). The main flat circular surface of the end cap should now align with the edge of a semicircular groove that runs all around the vent screw. This is to visually confirm that the vent screw has been properly tightened.

Result

When the battery is fully charged the charger will start trickle charging the battery. It is not recommended to trickle charge the battery for a long time. It is better to fast charge, and then top up the battery just before operation.

Further requirements

Caution _____

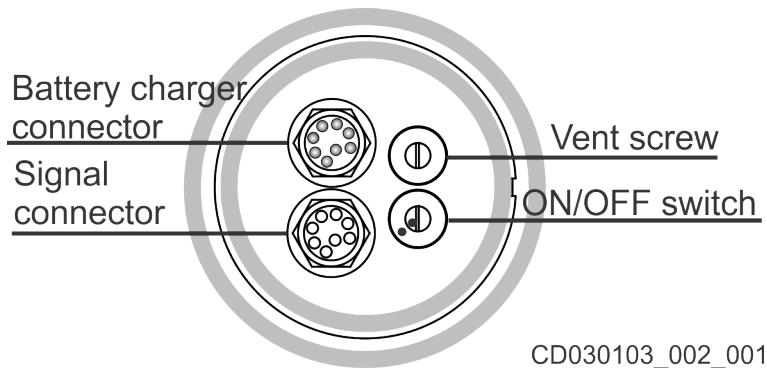
When the charging is done, always make sure the vent screw is closed.

Deploying the transponder with the vent screw open will ruin the transponder.

Powering up the transponder

Before deploying the transponder you must connect the battery to the internal circuitry.

Procedure



- 1 See the alignment markers on the ON/OFF switch.
- 2 Align the markers using a suitable screwdriver.

Result

The unit transmits bursts when switched on.

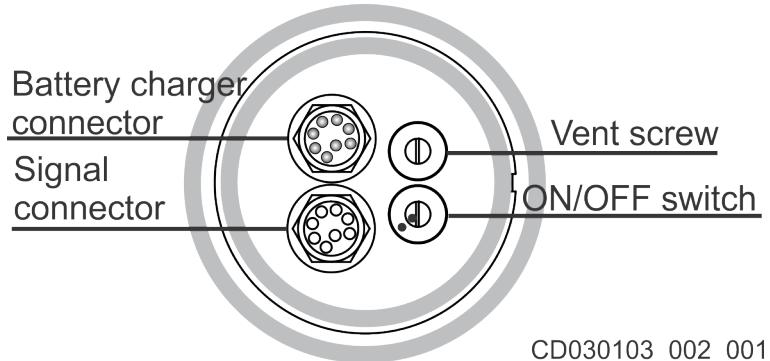
Each time the transponder is switched on, it resets to the two default channels.

Note _____

Always make sure the vent screw is closed before deployment.

Powering down the transponder

Procedure



- Use a suitable screwdriver to move the two marker dots away from each other.

Result

The transponder is off in all three other positions.

Note

Always keep the transponder switched off when not in use.

Always make sure the vent screw is closed before deployment.

Responder function

Procedure

- cNODE will automatically change to responder mode if a responder trigger signal is present. cNODE will change back to transponder mode if no new trigger signal is received within the next 30 seconds.

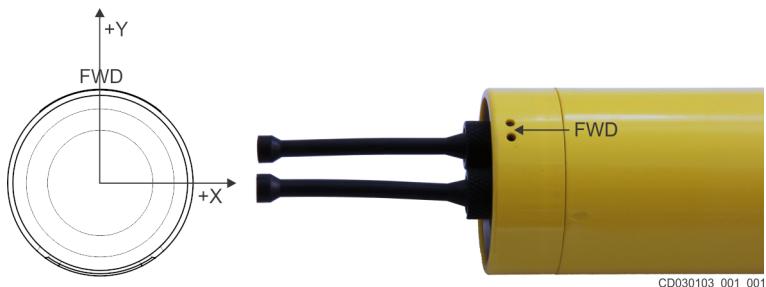
Result

See APOS online help for setting up a responder.

Setting up the internal tilt sensor

The transponder needs to face the right way to show the correct values.

Procedure



- Top view of the transponder to the left in this figure - showing the FWD direction. FWD is marked with the two holes in the bottom end cap module.

Configuring the transponder

The transponder channel and mode can be changed.

Prerequisites

The transponder is configured by Kongsberg Maritime. The channel and mode (FSK or cymbal) may be changed if required. The procedure to change configurations depends on the HiPAP/HPR system in use.

Procedure

- Change the channel and mode either by acoustic telemetry from a HiPAP system or via serial line from a Transponder Test and Configuration unit.
See APOS online help or the instruction manual for the TTC.

Maintenance

Topics

- [Charging the transponder, page 24](#)
- [Cleaning the transponder, page 25](#)
- [Inserting an O-ring, page 25](#)
- [Opening the transponder, page 26](#)
- [Changing the transducer, page 26](#)
- [Lubricating the subsea connector, page 27](#)

Charging the transponder

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Prerequisites

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- 4 Connect the charger plug to the connector on the transponder marked CHARGE.
- 5 Connect Power supply to mains (110 or 220 VAC).
- 6 Switch on the charger.

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- 8 Disconnect the charger plug from the transponder.
- 9 Close the vent screw.

Tighten the vent screw by hand only, until you feel a rather sudden resistance. (an internal axial O-ring hits a metal surface, compresses 0.3 mm, before 2 metal surfaces meet). The main flat circular surface of the end cap should now align with the edge of a semicircular groove that runs all around the vent screw. This is to visually confirm that the vent screw has been properly tightened.

Result

When the battery is fully charged the charger will start trickle charging the battery. It is not recommended to trickle charge the battery for a long time. It is better to fast charge, and then top up the battery just before operation.

Further requirements

Caution _____

When the charging is done, always make sure the vent screw is closed.

Deploying the transponder with the vent screw open will ruin the transponder.

Cleaning the transponder

The transponder must be cleaned after use.

Procedure

- 1 Remove any growth and dirt with a stiff brush or a wooden or plastic scraper. Be careful not to damage the transducer.
- 2 Clean the unit thoroughly with lots of fresh water.
- 3 Dry off, so no water can come inside when opening.

Inserting an O-ring

The O-rings must be inspected for damage as often as possible.

Procedure

Note _____

Make sure to keep the O-rings and mating surfaces free of dust and debris.

Do not use a screwdriver or similar when removing the O-ring, use an O-ring tool.

- 1 Open the transponder.
- 2 Remove the existing O-ring.
- 3 Clean the surface and cover it with a thin film of silicone grease.
Use lint-free objects when cleaning the surfaces.
- 4 Insert the new O-ring.

- 5 Close the transponder.

Opening the transponder

In order to replace the transponder battery - and to access the electronic module for maintenance - the unit must be opened.

Prerequisites

The transponder must be cleaned and dried before opening, so that no dirt or water seeps into the unit when it is opened.

Procedure

- 1 Pull out the lock cord between the tube and the end cap.
If the lock cord is hard to remove, try carefully opening the vent screw. Pressure may have built up inside the transponder.
- 2 Remove the end cap.
There is a 5 mm orientation peg at either end of the tube. When pulling apart, make sure to keep this orientation until all parts are completely free from each other. Forceful twisting of the parts relative to each other while the internal parts are still mated, will damage the unit.
- 3 Pull out the lock cord between the transducer and the tube.
- 4 Remove the transducer carefully, the chassis and the battery is fastened to the transducer.
- 5 Replace the O-rings that are damaged or used for more than a year.
- 6 Make sure the mating surfaces and the O-rings are completely clean and wipe a thin film of silicone grease over the rings and mating surfaces.

Result

Follow the procedure for opening the transponder in reverse order to close it.

Changing the transducer

The transducer is a sealed unit and does not open. If the transducer is damaged, replace the whole unit.

Prerequisites

The transponder needs to be clean and open to change the transducer.

Procedure

- 1 Remove the battery carefully.
- 2 Unscrew the chassis from the transducer.
- 3 Make sure the new transducer is of the same type as the old.
- 4 Fasten the transducer to the chassis and fit the battery.

Further requirements

Assemble the transponder.

Lubricating the subsea connector

The subsea connector must be kept clean from grit and dirt.

Prerequisites*Caution* _____

Do not use silicone based sprays like 5–55, WD-40 or similar. These products will degrade the rubber fused around the metal pins.

Procedure

- 1 Remove the dummy plug or the external cable from the connector.
- 2 Apply Molykote 44M silicone based grease.
Half a match head dose per contact is enough.

Spare parts

Topics

- [cNODE Mini maintenance kit spare part, page 29](#)
- [TD40V spare part, page 29](#)
- [TD180 spare part, page 29](#)
- [TD80V spare part, page 30](#)
- [Split transponder \(S\) for remote transducer spare part, page 30](#)
- [Remote transducer TDR180 spare part, page 30](#)
- [Remote transducer TDR40V spare part, page 30](#)
- [Remote transducer TDR30H spare part, page 31](#)
- [Remote transducer TDR30V spare part, page 31](#)
- [Transducer cable 6 m spare part, page 31](#)
- [Depth sensor spare part, page 31](#)
- [Battery spare part, page 32](#)
- [Tube spare part, page 32](#)
- [End cap spare part, page 32](#)
- [Battery charger spare part, page 32](#)
- [Power supply spare part, page 33](#)
- [EMI Shield gasket - spare part, page 33](#)
- [Retainer cord - Spare part, page 33](#)
- [Transponder Test and Configuration unit \(TTC30\) spare part, page 33](#)

cNODE Mini maintenance kit spare part

- **Part name:** cNODE Mini maintenance kit
- **Part number:** 351794

The kit consists of:

- 2 locking cords
- 4 O-rings 58 mm
- 2 locking sleeves MCDLSF
- 1 female dummy plug
- 1 male dummy plug
- 1 O-ring 12 mm
- 1 O-ring 10 mm

TD40V spare part

Aluminium

- **Part name:** TD40V Mini Aluminium
- **Part number:** 332186



Stainless steel

- **Part name:** TD40V St Mini Steel
- **Part number:** 365401

TD180 spare part

Aluminium

- **Part name:** TD180 Mini Aluminium
- **Part number:** 333059



Stainless steel

- **Part name:** TD180 St Mini Steel
- **Part number:** 320885

TD80V spare part

- **Part name:** TD80V St Mini Steel
- **Part number:** 352910



Split transponder (S) for remote transducer spare part

Aluminium

- **Part name:** Split transponder (S) for remote transducer Aluminium
- **Part number:** 349750



Stainless steel

- **Part name:** Split transponder (S) for remote transducer Stainless steel
- **Part number:** 330071

Remote transducer TDR180 spare part

Aluminium



- **Part name:** Remote transducer TDR180
- **Part number:** 349742

Stainless steel

- **Part name:** Remote transducer TDR180
- **Part number:** 375361

Remote transducer TDR40V spare part

Aluminium



- **Part name:** Remote transducer TDR40V
- **Part number:** 349743

Stainless steel

- **Part name:** Remote transducer TDR40V
- **Part number:** 375360

Remote transducer TDR30H spare part

Aluminium



- **Part name:** Remote transducer TDR30H
- **Part number:** 345773

Stainless steel

- **Part name:** Remote transducer TDR30H
- **Part number:** 375359

Remote transducer TDR30V spare part

Aluminium



- **Part name:** Remote transducer TDR30V
- **Part number:** 333445

Stainless steel

- **Part name:** Remote transducer TDR30V
- **Part number:** 370447

Transducer cable 6 m spare part

- **Part name:** Transducer cable, 6 m
- **Part number:** 345772



Depth sensor spare part

Aluminium

- **Part name:** cNODE Mini Depth sensor
- **Part number:** 402525



Stainless steel

- **Part name:** cNODE Mini Depth sensor, steel
- **Part number:** 405689

Battery spare part

- **Part name:** Battery
- **Part number:** 290-220687



Tube spare part

Aluminium

- **Part name:** cNODE Tube aluminium
- **Part number:** 381346



Stainless steel

- **Part name:** cNODE Tube stainless steel
- **Part number:** 381343

End cap spare part

Aluminium

- **Part name:** cNODE Mini end cap aluminium
- **Part number:** 351794



Stainless steel

- **Part name:** cNODE Mini end cap steel
- **Part number:** 349131

Battery charger spare part

- **Part name:** Battery charger cNODE Mini
- **Part number:** 290-220687



Power supply spare part

Aluminium

- **Part name:** cNODE Power supply Aluminium
- **Part number:** 346471



Stainless steel

- **Part name:** cNODE Power supply Steel
- **Part number:** 367386

EMI Shield gasket - spare part

The Electromagnetic interference (EMI) shield gasket is used to establish a firm electrical connection between the outer body of the transponder and the end cap. This electrical connection is vital, because the end cap holds the sacrificial zinc anodes.

- **Part name:** Electromagnetic interference (EMI) shield gasket
- **Part number:** 314433

Retainer cord - Spare part

The plastic retainer cord is used to secure and hold the end caps in place when the transponder housing is closed.

- **Part name:** Retainer cord
- **Part number:** 314415

Transponder Test and Configuration unit (TTC30) spare part

- **Part name:** TTC 30
- **Part number:** 345775



Technical specifications

Topics

- [Performance specification, page 35](#)
- [Weight and outline dimensions, page 37](#)
- [Power specifications, page 39](#)
- [Environmental specifications, page 40](#)

Performance specification

These performance specifications summarize the main functional and operational characteristics of the cNODE Mini.

cNODE Mini 3x series

- **Frequency band:** Medium frequency (MF)
- **Maximum depth rating:** 4000 m

Internal tilt

- **Max. detectable angles:** $\pm 90^\circ$
- **Accuracy:** $\pm 2^\circ$

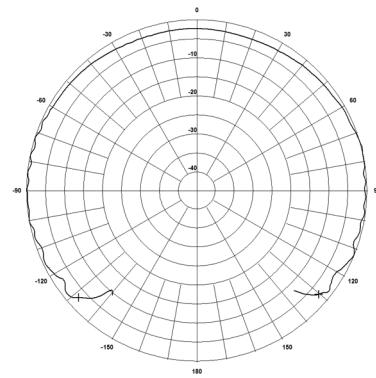
Responder trigger signal

Responder trigger connection via the external signal connector.

- **Logic pulse:** Positive
- **Amplitude:** 5 to 25 V
- **Duration:** 2 to 6 ms

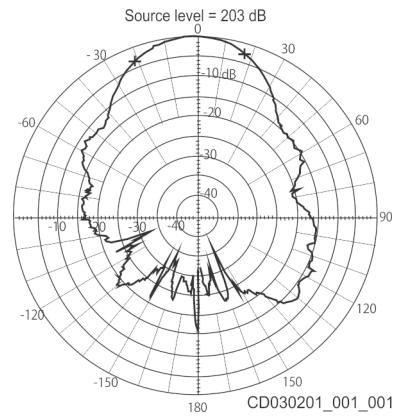
TD180

- **Beam pattern:**
- **Transducer beam:** 180° vertical
- **Frequency band:** Medium frequency
- **Receiver sensitivity:** 100 dB
- **Maximum source levels:**
 - Max 190 dB
 - High 184 dB
 - Low 178 dB
 - Min 173 dB



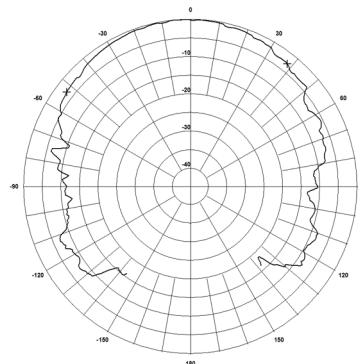
TD40V

- **Beam pattern:**
- **Transducer beam:** 40° vertical
- **Frequency band:** Medium frequency
- **Receiver sensitivity:** 90 dB
- **Maximum source levels:**
 - Max 203 dB
 - High 197 dB
 - Low 191 dB
 - Min 183 dB



TD80V

- **Beam pattern:**
- **Transducer beam:** 80° vertical
- **Frequency band:** Medium frequency
- **Receiver sensitivity:** 85 dB
- **Maximum source levels:**
 - Max 188 dB
 - High 182 dB
 - Low 176 dB
 - Min 171 dB



Battery charger

- **Charge method:** Constant current, charging the three battery strings individually
- **Detection method for fully charged battery:** Temperature rise, maximum temperature and maximum time (165 min.)
- **Charging time:** 2 hours 45 minutes for an empty battery

Weight and outline dimensions

These weights and outline dimension characteristics summarize the physical properties of the cNODE Mini.

cNODE Mini

Transponder	Weight in air	Weight in water	Height	Diameter
cNODE Mini 34–40V	6.7 kg	3.4 kg	600 mm	85 mm
cNODE Mini 34–180	6.7 kg	3.4 kg	598 mm	85 mm
cNODE Mini 31–80V-D-St	15.4 kg	11.4 kg	718 mm	85 mm

TD180

- **Height:** 70.5 mm
- **Diameter:** Ø88 mm

TD40V

- **Height:** 71 mm
- **Diameter:** Ø100 mm

TD30H

- **Height:** 123 mm
- **Diameter:** Ø77 mm

TD80V

- **Height:** 36.5 mm
- **Diameter:** Ø80 mm

Remote transducer TDR180

- **Height:** 209.8 mm
- **Diameter:** Ø 88 mm

Remote transducer TDR40V

- **Height:** 218.6 mm
- **Diameter:** Ø 100 mm

Remote transducer TDR30H

- **Height:** 262.4 mm

- **Diameter:** Ø 77 mm

Remote transducer TDR30V

- **Height:** 279.5 mm
- **Diameter:** Ø 166mm

Transducer cable for remote transducers

- **Length:** 6 m

Split transponder (S) for remote transducer

- **Height:** 31.5 mm
- **Diameter:** Ø85 mm

Depth sensor (D)

- **Height:** 154 mm
- **Diameter:** Ø85 mm

Tube

- **Height:** 495 mm
- **Diameter:** Ø85 mm

Basic end cap

- **Height:** 31.5 mm
- **Diameter:** Ø85 mm

Floating collar

- **Height:** 845 mm
- **Width:** 290 mm

Power supply

- **Height:** 309.2 mm
- **Diameter:** Ø85 mm

Battery charger

Weight	Height	Width	Depth
2.9 kg	83 mm	256 mm	355 mm

Power specifications

These power characteristics summarize the power specifications for the cNODE Mini.

cNODE Mini battery lifetime

- **Quiescent:** 60 days

Mini 34–180 series – Cymbol and Mini 31–180 series – Cymbol

Update rate	1 seconds [days]	2 seconds [days]	3 seconds [days]	4 seconds [days]	5 seconds [days]	10 seconds [days]
TX power level						
Minimum	5.7	6.0	6.1	6.2	6.2	6.3
Low	4.2	5.1	5.4	5.6	5.8	6.1
High	2.1	3.2	3.8	4.2	4.5	5.3
Maximum	0.5	1.1	1.5	1.9	2.2	3.3

Mini 34–180 series – FSK and Mini 31–180 series – FSK

Update rate	1 seconds [days]	2 seconds [days]	3 seconds [days]	4 seconds [days]	5 seconds [days]	10 seconds [days]
TX power level						
Minimum	10.1	10.4	10.5	10.6	10.6	10.7
Low	8.5	9.5	9.9	10.1	10.2	10.5
High	5.3	7.1	8.0	8.5	8.9	9.7
Maximum	1.8	3.1	4.1	4.8	5.4	7.3

Mini 34–40V series – Cymbol and Mini 31–40V series – Cymbol

Update rate	1 seconds [days]	2 seconds [days]	3 seconds [days]	4 seconds [days]	5 seconds [days]	10 seconds [days]
TX power level						
Minimum	5.7	6.0	6.1	6.2	6.2	6.3
Low	3.5	4.5	5.0	5.3	5.5	5.9
High	1.2	2.1	2.8	3.3	3.6	4.6
Maximum	0.3	0.6	0.9	1.2	1.5	2.4

Mini 34–40V series – FSK and Mini 31–40V series – FSK

Update rate	1 seconds [days]	2 seconds [days]	3 seconds [days]	4 seconds [days]	5 seconds [days]	10 seconds [days]
TX power level						
Minimum	10.1	10.4	10.5	10.6	10.6	10.7
Low	7.5	8.8	9.4	9.7	9.9	10.3
High	3.6	5.4	6.5	7.2	7.8	9.0
Maximum	1.1	2.0	2.8	3.4	3.9	5.8

Battery charger

- **Voltage requirement:** 110 or 220 V

Environmental specifications

These environmental specifications summarize the temperature and humidity requirements for the cNODE Mini.

All cNODE Mini transponders

- **Operational temperature:** -5 to +55°C
- **Storage temperature:** -40 to +70°C

Battery

- **Operational temperature:** -5 to +55°C
- **Storage temperature:** -20 to +30°C
- **Storage humidity:** <50% relative

Battery charger

- **Operational temperature:** 5 to 40°C for fast charging
- **Storage temperature:** -40 to +70°C
- **Relative humidity:** 10 to 90% relative non-condensing
- **Ingress protection:** IP30

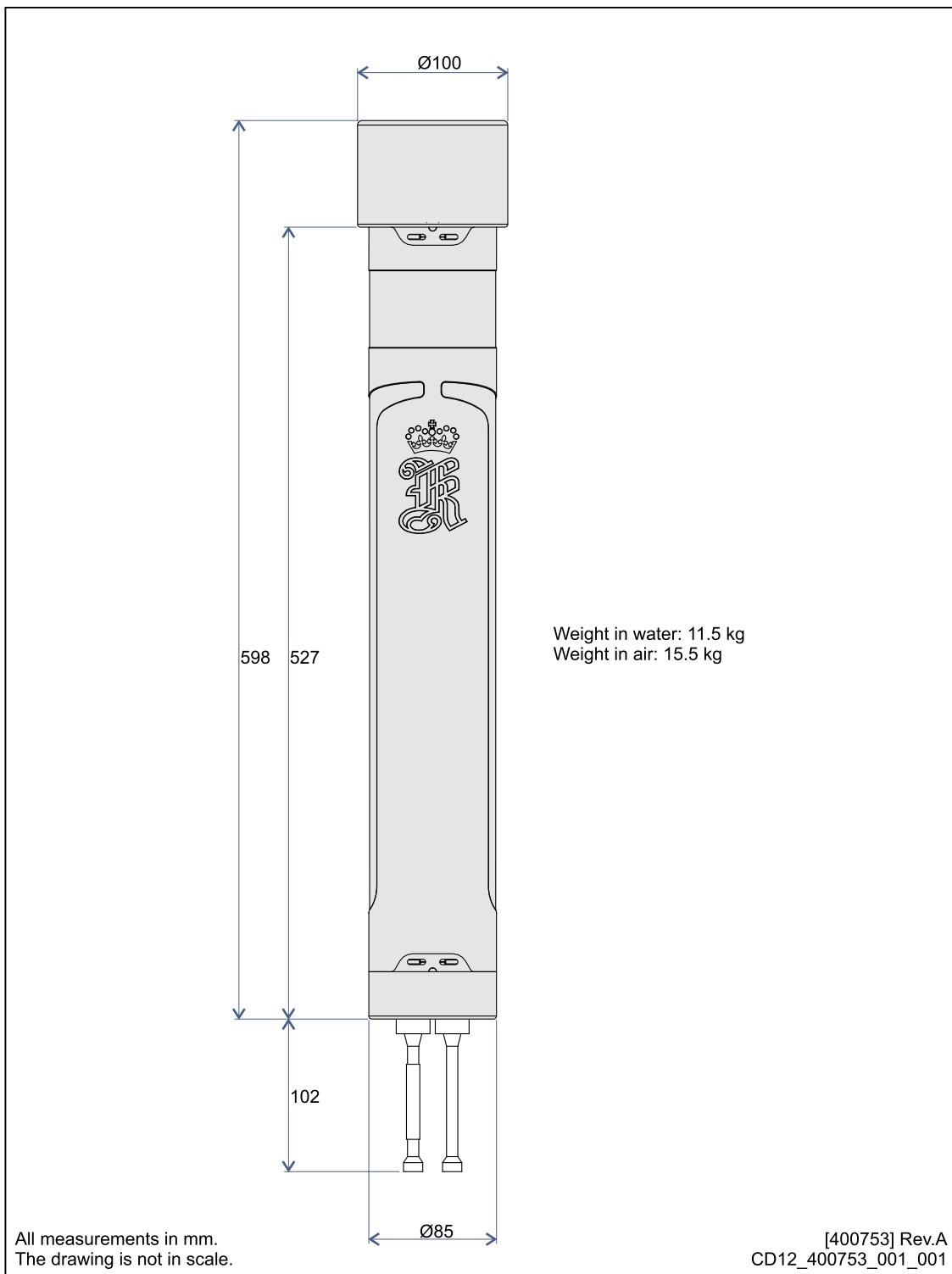
Drawing file

Topics

- [cNODE Mini 31-40V-St outline dimensions, page 42](#)
- [cNODE Mini 34-180 outline dimensions, page 43](#)
- [cNODE Mini 34-40V outline dimensions, page 44](#)
- [cNODE Mini 3x-180-D outline dimensions, page 45](#)
- [cNODE Mini 3x-80V-D-St outline dimensions, page 46](#)
- [cNODE Mini 31-80V-St outline dimensions, page 47](#)

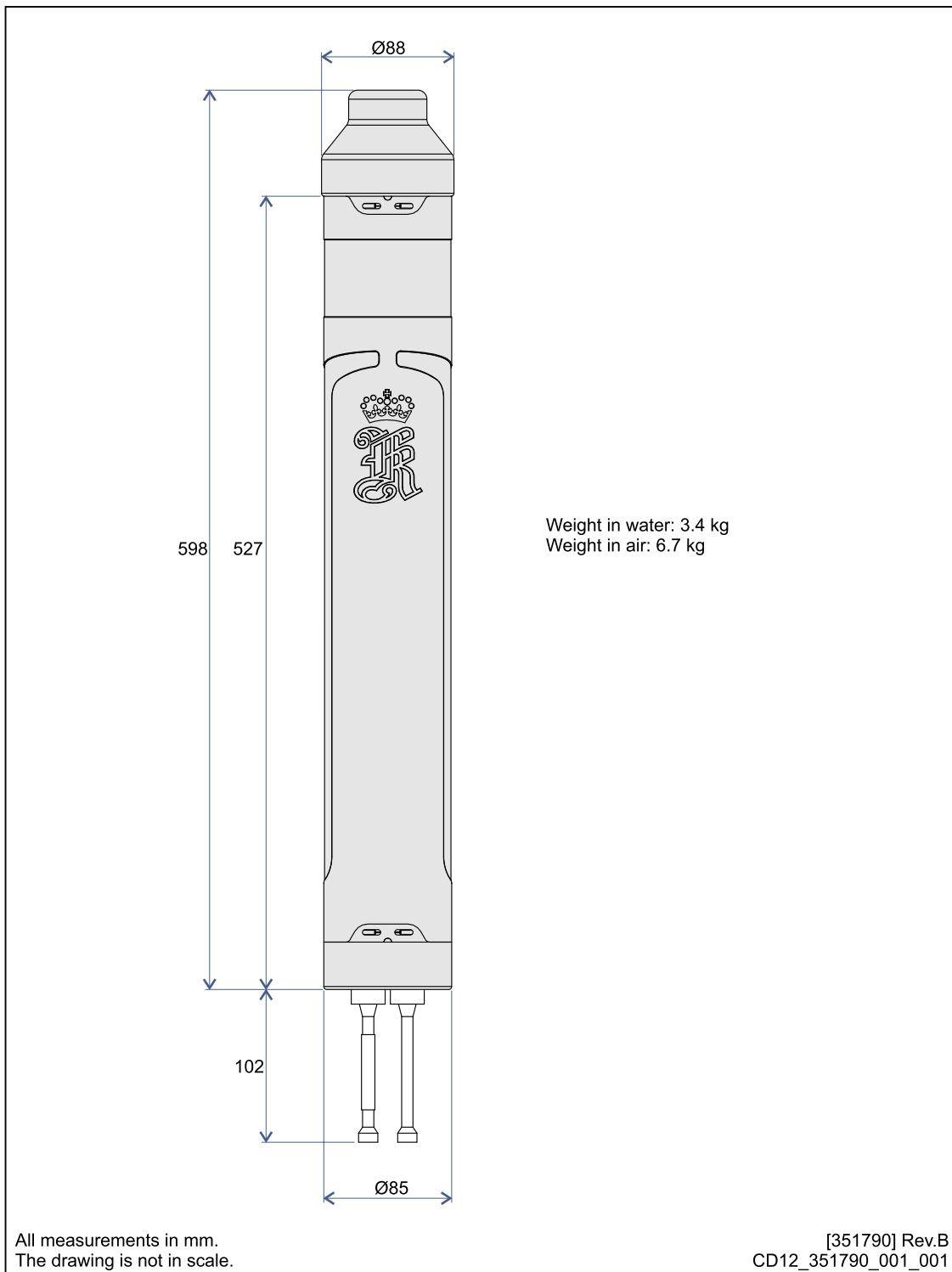
cNODE Mini 31-40V-St outline dimensions

Drawing 400753



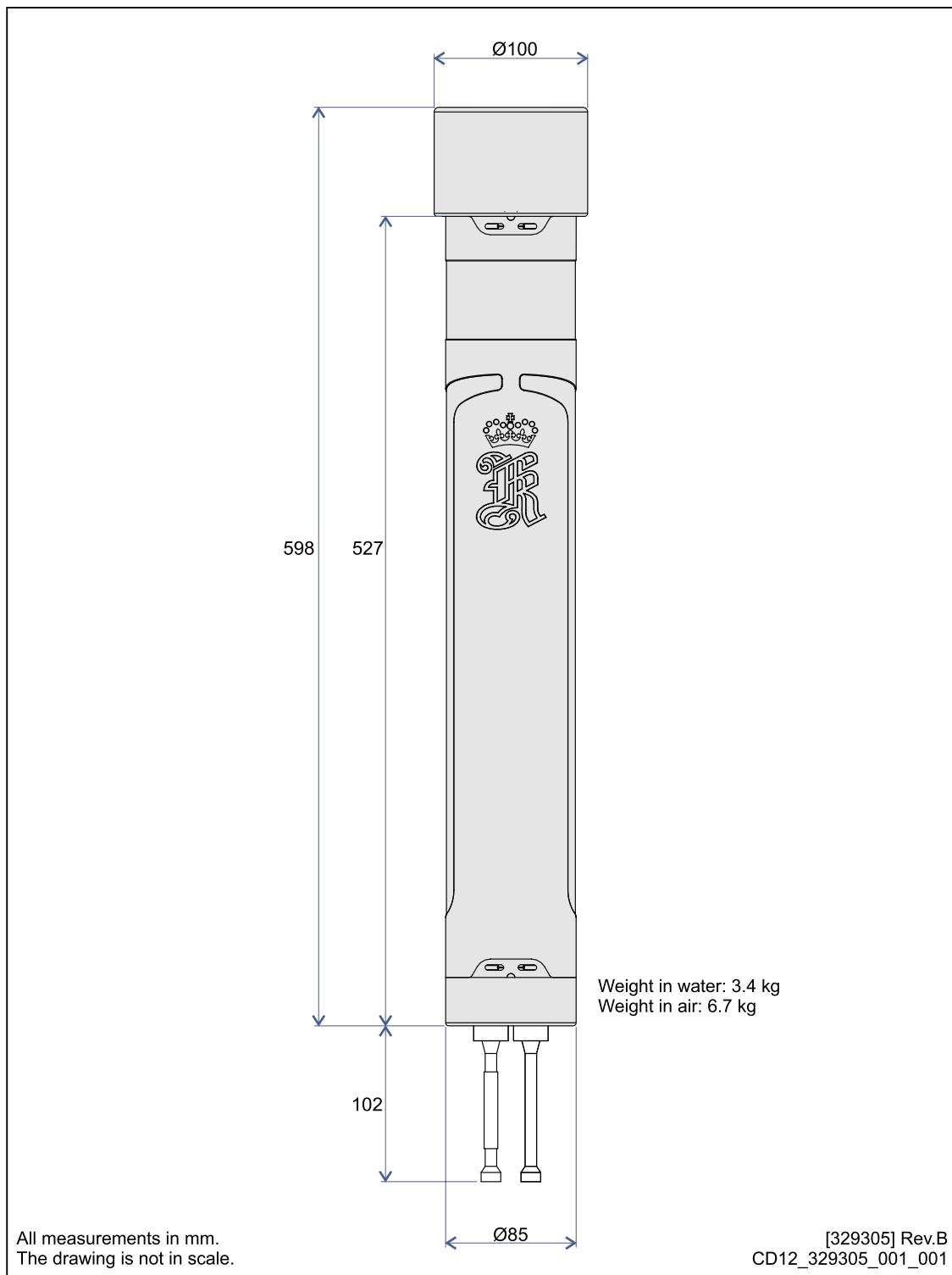
cNODE Mini 34-180 outline dimensions

Drawing 351790



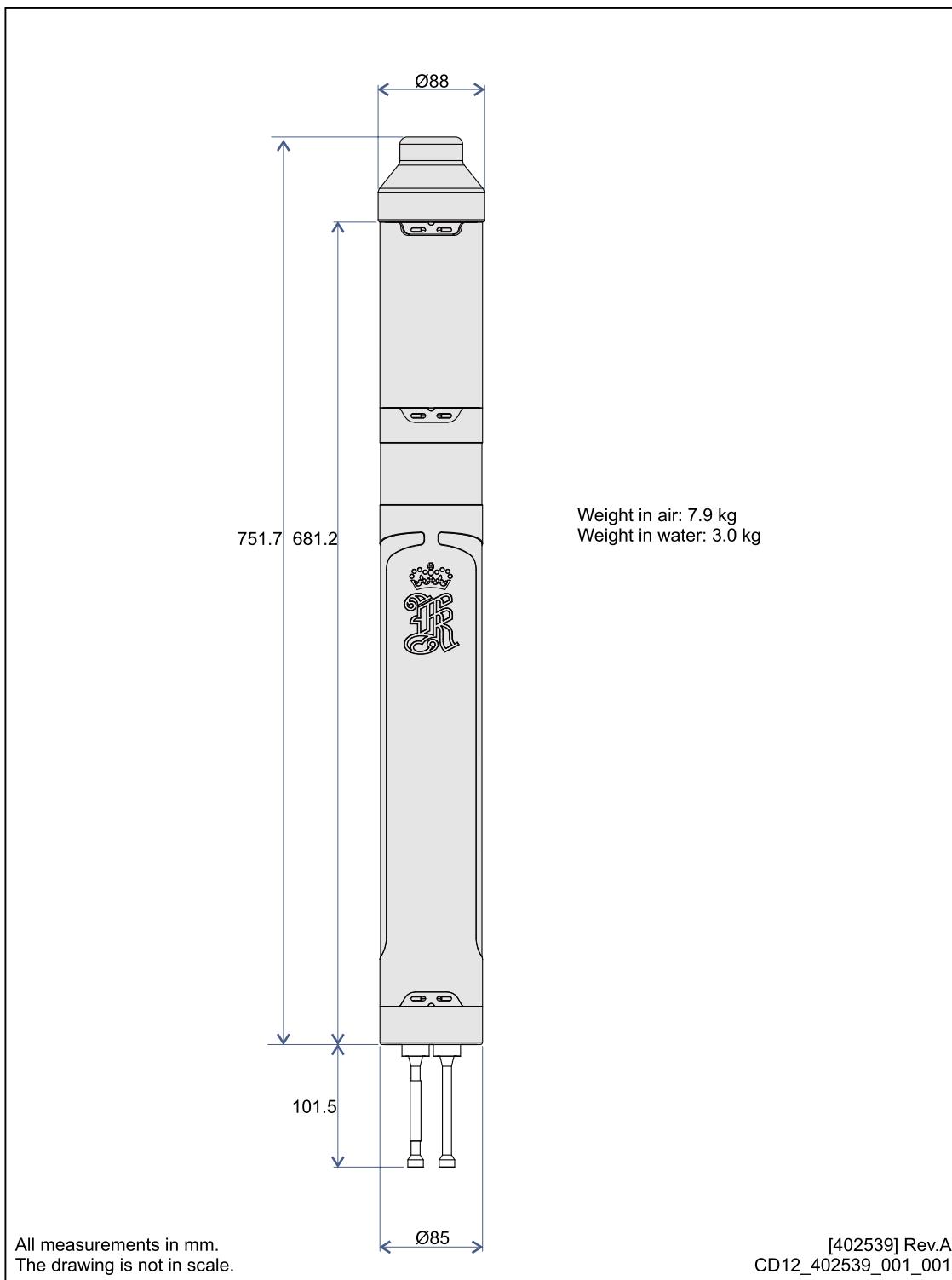
cNODE Mini 34-40V outline dimensions

Drawing 329305



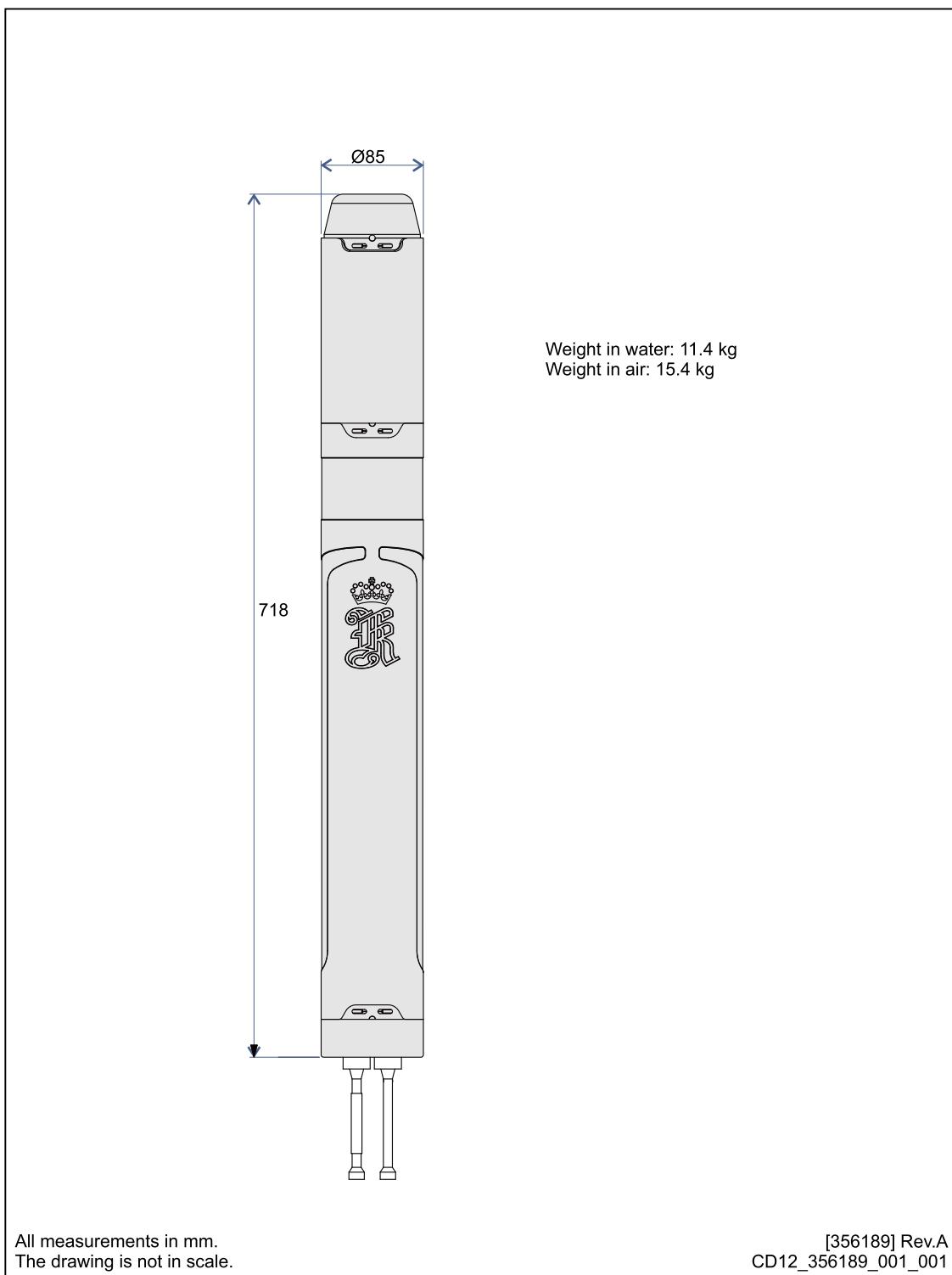
cNODE Mini 3x-180-D outline dimensions

Drawing 402539



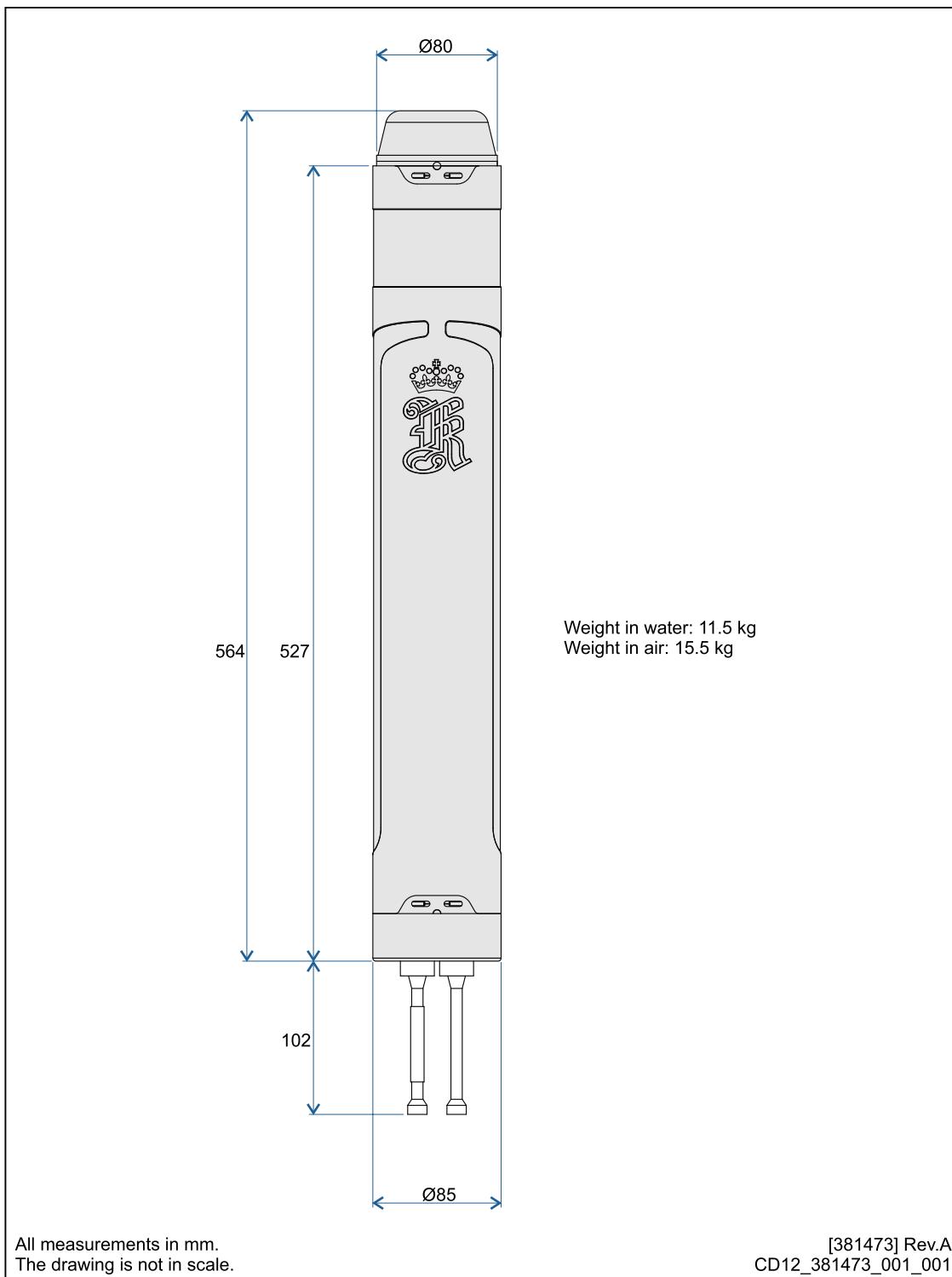
cNODE Mini 3x-80V-D-St outline dimensions

Drawing 356189



cNODE Mini 31-80V-St outline dimensions

Drawing 381473



Index

290-220687	
battery charger (spare part).....	32
290-220687	
battery (spare part).....	32
314415	
retainer cord (spare part).....	33
314433	
electromagnetic interference (EMI) shield gasket (spare part).....	33
320885	
TD180 St (spare part)	29
332186	
TD40V (spare part).....	29
TD80V (spare part).....	30
333059	
TD180 (spare part).....	29
345775	
TTC 30 (spare part).....	33
346471	
power supply (spare part).....	33
349750	
split transponder (S) for remote transducer (spare part)	30
351794	
maintenance kit (spare part).....	29
365401	
TD40V St (spare part).....	29
367386	
power supply (spare part).....	33
381343	
tube (spare part).....	32
381346	
tube (spare part).....	32
402525	
depth sensor (spare part).....	31
405689	
depth sensor (spare part).....	31
A	
about	
battery	11
battery charger	11
depth sensor	10
description	7
naming description	7
power supply	11
transducer	9
TTC.....	11
tube	10
activate	
responder function	21
audience	
this manual.....	5
B	
battery	
description	11
spare part.....	32
C	
cables	
interconnection.....	14
interface	14
layout	14
characteristics	
performance	35
charging	
transponder	19, 24
cleaning	
transponder	25
configuration	
transponder	22
configuring	
transponder	22
D	
depth sensor	
description	10
spare part.....	31
description	
battery	11
battery charger	11
depth sensor	10
naming	7
power supply	11
system	7
transducer	9
TTC	11
tube	10
dimensions	
specifications	37
drawing	
system diagram.....	8
E	
electromagnetic interference (EMI) shield gasket	
spare part.....	33
EMI shield gasket	
spare part.....	33
end cap	
top.....	26
environmental	
requirements.....	40
equipment	
handling	12
receipt	12

responsibility	12	power supply	33
storage.....	12	TTC 30	33
F		outline dimensions	
functional		specifications	37
diagram.....	8		
G		P	
general supply conditions.....	12	performance	
equipment responsibility.....	12	specifications	35
receipt	12	pin out	
storage.....	12	end cap connectors.....	15
unpacking.....	12	power converter connectors	16
H		power	
how to		requirements	39
open the transponder	26	power converter	
humidity		description	11
requirements	40	pin out	16
I		power down	
information		transponder	21
support	13	power supply	
inserting		description	11
o-ring	25	spare part.....	33
interconnection		power up	
cables	14	transponder	20
interface		pressure sensor	
cables	14	description	10
K		spare part.....	31
Kongsberg Maritime		procedure	
support	13	opening the transponder.....	26
L		publication	
lubricating		purpose	5
subsea connector	27	target audience	5
M		purpose	
maintenance kit		this manual.....	5
spare part.....	29	R	
manual		reader	
purpose	5	this manual.....	5
target audience	5	receipt	
N		general supply conditions.....	12
naming		registered trademarks.....	5
description	7	remote transducer	
O		TDR180	30
o-ring		remote transducer cable	
inserting	25	spare parts.....	31
open		remote transducer TDR30H	
transponder	26	spare parts.....	31
order number		remote transducer TDR30V	
		spare parts.....	31
		remote transducer TDR40V	
		spare parts.....	30
		replacement	
		transducer	26
		requirements	
		environmental	40
		humidity.....	40
		power	39
		temperature	40
		responder	
		activate	21
		responsibility	
		equipment	12
		retainer cord	
		spare part.....	33

S

scope of supply.....	11
spare part.....	28
battery	32
battery charger	32
depth sensor	31
electromagnetic interference (EMI) shield	
gasket	33
maintenance kit	29
power supply	33
retainer cord	33
split transponder (S) for remote transducer	30
TD180	29
TD180 St.....	29
TD40V	29
TD40V St.....	29
TD80V	30
TTC 30	33
tube	32
spare parts	
remote transducer cable	31
remote transducer TDR30H	31
remote transducer TDR30V	31
remote transducer TDR40V	30
TDR180	30
TDR30H	31
TDR30V	31
TDR40V	30
specifications	
dimensions.....	37
outline dimensions.....	37
performance	35
weight	37
split transponder (S) for remote transducer	
spare part.....	30
standard items	
provided with the delivery.....	11
start	
transponder	20
stop	
transponder	21
storage	
general supply conditions.....	12
subsea connector	
lubricating.....	27
supply conditions	12
equipment responsibility.....	12
receipt	12
storage	12
unpacking	12
support information.....	13
system	
diagram.....	8
system description	7
system units	
transducer	9

T

target audience	
this manual.....	5
TD180	
spare part.....	29
weight and outline dimensions.....	37

TD180 St

spare part.....	29
-----------------	----

TD30H

weight and outline dimensions.....	37
------------------------------------	----

TD40V

spare part.....	29
-----------------	----

TD40V St

spare part.....	29
-----------------	----

TD80V

spare part.....	30
-----------------	----

weight and outline dimensions.....	37
------------------------------------	----

TDR180

remote transducer	30
-------------------------	----

spare parts.....	30
------------------	----

TDR30H

spare parts.....	31
------------------	----

TDR30V

spare parts.....	31
------------------	----

TDR40V

spare parts.....	30
------------------	----

temperature

requirements.....	40
-------------------	----

this manual

purpose	5
---------------	---

target audience	5
-----------------------	---

tilt sensor

internal	22
----------------	----

top end cap

open.....	26
-----------	----

trademarks

registered.....	5
-----------------	---

transducer

description	9
-------------------	---

replacement.....	26
------------------	----

transponder

charging	19, 24
----------------	--------

cleaning	25
----------------	----

configuration.....	22
--------------------	----

open.....	26
-----------	----

power down.....	21
-----------------	----

power up	20
----------------	----

start	20
-------------	----

stop	21
------------	----

tilt sensor	22
-------------------	----

transponder test and configuration unit

description	11
-------------------	----

TTC

description	11
-------------------	----

TTC 30

spare part.....	33
-----------------	----

tube

description	10
-------------------	----

spare part.....	32
-----------------	----

U

unpacking

general supply conditions.....	12
--------------------------------	----

W

weight

specifications	37
----------------------	----

weight and outline dimensions	
TD180	37
TD30H	37
TD40V	37
TD80V	37
wiring	
end cap connectors.....	15
information	14
power converter connectors	16

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