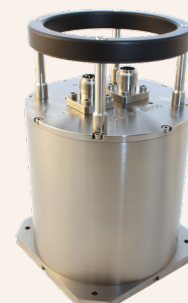


MGC® R2 SB50



KONGSBERG



Gyro compass and Inertial Navigation System (INS)

This MGC R2 SB50 product is a combined motion sensing and gyro compass mounted in a subsea bottle depth rated to 100 meters. The MGC R2 SB50 includes three Ring Laser Gyros and three linear accelerometers.

Typical applications

The MGC R2 SB50 is designed for portable seabed mapping systems where the MGC is to be mounted on the multibeam transducer head. With input of data from a GNSS system, the MGC R2 SB50 is a fully inertial navigation system (INS). It can output heading, roll, pitch, heave and position. Acceleration and velocity of linear motions, as well as angular rates, are output from the unit. The MGC product outputs both processed and raw (gyro and accelerometer) sensor data.

The proven PFreeHeave® algorithms are part of the navigation algorithms that enable down to 1 cm accuracy in delayed heave output and 5 cm accuracy in real-time heave output. The linear position and velocity measurements can be output in up to four different points on the vessel.

Function

The MGC can operate in AHRS mode and Integrated Navigation mode. In the AHRS mode, only input of speed is required. In this mode the product will output heading, roll, pitch and heave accurately. In the Integrated Navigation mode, input of speed, position and PPS from a GNSS system is required (VTG, GGA, ZDA). In this mode the product will output heading, roll, pitch, heave and position.

The unit is delivered with a Windows based configuration and data presentation software, the MRC+. In this software vector arms from where the MGC is mounted to the center of gravity (CG) and two individually configurable monitoring points (MPs), can be defined. The heave measurements can be output in four different locations (the MGC itself, CG, MP1 and MP2) simultaneously on serial lines or Ethernet ports. A typical monitoring point is the echo sounder transducer head.

Variables output

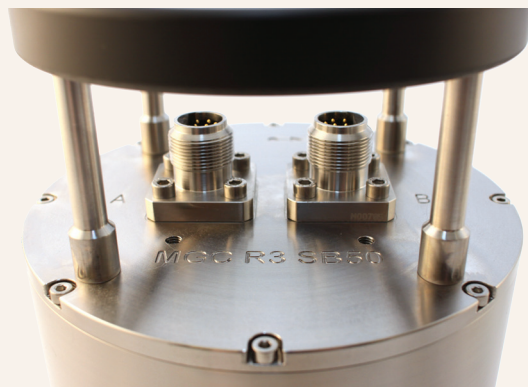
The MGC outputs heading, roll and pitch and corresponding angular rate vectors. The unit outputs relative (dynamic) heave position, velocity and acceleration. In the Integrated Navigation mode it also outputs absolute position in north and east direction in addition to height above the ellipsoid.

Digital I/O protocols

MGC data is available through both Ethernet interface and serial lines enabling easy distribution of data to multiple users on board the vessel. Output protocols for commonly used survey equipment are available on two individually configurable serial lines and Ethernet/UDP.

FEATURES

- 0.005° roll and pitch dynamic accuracy
- 0.1° heading accuracy GNSS aided
- Includes INS capability
- Delivered in titanium housing, depth rated to 100 metres
- Outputs on RS-232, RS-422 and Ethernet
- High output data rate (200 Hz)
- Precise heave at long wave periods by use of PFreeHeave® algorithms
- Lever arm compensation to two individually configurable monitoring points
- Small size and low power consumption
- Each MGC delivered with a Calibration Certificate
- Selectable communication protocols in the Windows based configuration software



Technical specifications

MGC® R2 SB50

Orientation output

| | |
|--|----------------------|
| Angular orientation range | ±180° |
| Resolution in all axes | 0.0001° |
| Static accuracy roll, pitch | 0.02° RMS |
| Dynamic accuracy roll, pitch | 0.005° 1-sigma |
| Accuracy heading | 0.15° RMS sec.lat |
| Accuracy heading (GNSS aided) | 0.1° RMS sec.lat |
| Heading settling time to data available | <5 min from start-up |
| Heading settling time to full accuracy (typical) | 17 min from start-up |

Gyro output

| | |
|--------------------|---------|
| Angular rate range | ±125°/s |
|--------------------|---------|

Acceleration output

| | |
|-------------------------------|----------------------|
| Acceleration range (all axes) | ±45 m/s ² |
|-------------------------------|----------------------|

Heave output

| | |
|----------------------------|---------------------------------|
| Output range | ±50 m, adjustable |
| Periods (real-time) | 0 - 25 s |
| Periods (delayed) | 0 - 50 s |
| Heave accuracy (real-time) | 5 cm or 5% whichever is highest |
| Heave accuracy (delayed) | 1 cm or 1% whichever is highest |

Position output

| | |
|----------------------------|--------|
| Free inertial (GNSS aided) | 5 nm/h |
|----------------------------|--------|

Electrical

| | |
|--------------------------|--|
| Voltage input | 24 VDC nominal (18 - 32 VDC) |
| Power consumption | Max 12 W (typical 11 W) |
| Serial ports: | |
| • Com1 | Bidirectional RS-422 |
| • Com2 | Output only, RS-232 |
| • Com3 & Com4 | Input only, user configurable RS-232, RS-422 |
| Ethernet output ports | 5 |
| Ethernet UPD/IP | 10/100 Mbps |
| Digital output variables | 24 (max), Serial or Ethernet |
| Data output rate (max) | 200 Hz |
| Timing | < 1 ms |

Input formats

NMEA 0183, incl. GGA, VBW, VTG, ZDA or MRU Normal format

Output formats

| | |
|--|-----------------|
| - MRU normal | - Sounder |
| - NMEA 0183 proprietary | - EM3000 |
| - Atlas Fansweep | - TSS1 |
| - Seapath binary 23, 25, 26 | - PFreeHeave® |
| - KM binary | - MDL Trim Cube |
| - RDI ADCP | - Tokimec PTVG |
| - NMEA GGA, GLL, HDT, THS, ROT, VTG, GST, VER, HCR | |

Other data

| | |
|------------------------------|-----------------------------------|
| MTBF (computed) | 50000 h |
| MTBF (service history based) | 100000 h |
| Material | Titanium |
| Connector | 2 × 8-pin Seacon 5506-1508 (male) |

Weights and dimensions

| | |
|--------------------|--------------------|
| Dry weight | 10.5 kg |
| Submerged weight | 5.5 kg |
| Dimensions (HxLxW) | 275 × 184 × 184 mm |

Environmental specifications

| | |
|-------------------------|--------------------|
| Operational temperature | -15 °C - +55 °C |
| Storage temperature | -25 °C - +70 °C |
| Enclosure protection | IP68 |
| Vibration | IEC 60945/EN 60945 |

Electromagnetic compatibility

| | |
|--------------------------------------|--------------------|
| Compliance to EMC, immunity/emission | IEC 60945/EN 60945 |
|--------------------------------------|--------------------|

Specifications subject to change without any further notice.