DPS i4





SENSOR FUSIONED GNSS SOLUTION FOR DYNAMIC POSITIONING

By the introduction of the DPS i-series, KONGSBERG fuses decades of experience within GNSS and inertial technology in order to create a fully scalable and future-proof reference solution with emphasis on operational efficiency for DP applications.

Sensors teaming up

An unmatched integration of the latest within multi GNSS and KONGSBERG's unique motion gyro compass (MGC^{TM}) facilitate the possibility to operate with no additional augmentation services without compromising on DP performance. The DPS i-series is still fully prepared to utilize differential corrections and SBAS services when required. DPS i4 utilizes data from all available GNSS constellations including GPS, GLONASS, Galileo and BeiDou.

Designed for robust performance

The integration ensures a continuous position solution by bridging gaps in the GNSS reception and increasing position stability in periods with limited GNSS availability due to masking, scintillation and interference. GNSS and INS are perfectly matched as they overcome each others limitations. Using both systems is superior to using either system alone. RAIM (Receiver Autonomous Integrity Monitoring) extended by data from the INS provides ultimate reliability of the position and velocity data under difficult GNSS conditions.

Multi-use of sensor

By using the MGC as the inertial sensor, a high-quality WheelMark gyro compass becomes a part of the solution. In addition, MGC can serve other on-board systems such as navigation equipment and other systems that require attitude data.

Increased operational efficiency

Inertial technology combined with the latest multiconstellation GNSS technology enables a cost efficient and reliable position reference solution. No regular maintenance, calibration or additional operational costs are required.

Scalable solution

The flexible design of the DPS i-series ensures a scalable and expandable reference solution that can adapt to the specific requirements of any vessel. For the more demanding applications, a combination of multiple DPS systems and MGC/MRU sensors will enable precise heading determination world wide and provide spoofing detection capabilities. The DPS i-series may utilize existing or dedicated MGC or MRU sensors for the integration.

Active decision support

The DPS i-series has an intuitive and easy-to-use graphical user interface developed in close co-operation with experienced DP operators. The HMI (Human-Machine Interface) enables the operators to assess the quality of their positioning quickly and effectively during operation.

Remote service

The DPS i-series is ready for K-IMS remote services for operational support and troubleshooting. Cases that previously required a visit from a service engineer, may now be resolved remotely.

Highly optimized integration of INS and GNSS without the use of 3rd party DGNSS services

Dual frequency ionospheric compensation

• INS aided RAIM capability for enhanced integrity and reliability

Fully capable to utilize differential correction services if required

High-precision lever arm compensation of position and velocity

 Intuitive and easy-to-use HMI tailored to safety critical DP operations

• Scalable solution

• GNSS heading (requires two GPS systems)

• Spoofing detection capabilities

• Automatic data recording with replay functionality

• Remote service and diagnostics by utilizing K-IMS

TECHNICAL SPECIFICATIONS

DPS i4

PERFORMANCE

Non-differential position accuracy1

High precision accuracy² DGNSS position accuracy SBAS position accuracy

Velocity accuracy Roll, pitch accuracy

Update frequency rate¹

Latency

0.65 m 95% CEP < 10 cm, 95% CEP < 1 m, 95% CEP < 1 m, 95% CEP < 0.01 m/s, 95% CEP

Please see separate datasheets for MGC/MRU products

1-20/200 Hz

< 1 ms

All accuracy specifications are based on real-life tests conducted in the North Sea under various conditions. Operation in other locations under different conditions may produce different results.

INTERFACES

8 isolated ports, 6 configurable Serial ports

between RS-232 and RS-422

RS-422 Ethernet/LAN 4

DATA OUTPUTS

Message formats NMEA 0183 v. 3.0, Proprietary Message types ABBDP, ARABB, DPGGA, DTM, GBS, GGA, GLL, GNS, GRS, GSA,

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GST, GSV, RMC, VBW, VER,

VTG, ZDA

DATA INPUTS

DGNSS corrections RTCM-SC104 v.2.2, 2.3, 3.0 and

3.1, Seastar XP/XP2/G2/G2+/G4/

G4+

RTK corrections RTCM-SC104 v. 2.3, 3.0, 3.1 and

Gyro compass NMEA 0183 HDT, HRC, THS and Robertson LR22 BCD format

Display control DDC

INS SENSOR

Supported INS MGC R3, MGC R2, MRU 5+

(See dedicated datasheets for

technical information)

Integrated system

Dependent on subscription type

WEIGHTS AND DIMENSIONS

GNSS antenna

DPS i4 Processing Unit 5.4 kg, 89 x 485 x 357 mm DPS i-series HMI Unit 3.6 kg, 44 x 481 x 267 mm GNSS antenna 0.5 kg, 69 mm x 185 mm

POWER SPECIFICATIONS

DPS i4 Processing Unit 100 - 240 V AC, 50/60 Hz, max 75 W

HMI Unit

Processing Unit

External interface DP interface

DPS i-series HMI Unit 100 - 240 V AC, 50/60 Hz, max

170 W

GNSS antenna 5 V DC from Processing Unit

ENVIRONMENTAL SPECIFICATIONS

Operating temperature range

DPS i4 Processing Unit -15 to +55 °C (*) +5 to +35 °C (* DPS i-series HMI Unit GNSS antenna -40 to +85 °C (*) Recommended +5 to +40 °C (**) Recommended +20 °C

Humidity

DPS i4 Processing Unit Max 95 % non-condensing DPS i-series HMI Unit Max 90 % non-condensing GNSS antenna Hermetically sealed

Mechanical

TEC 60945/FN 60945, TACS F10 Vibration

Electromagnetic compatibility Compliance to EMC,

immunity/emission IEC 60945/EN 60945. IACS E10

Spectrum

Compliance to Article 3.2.

ETSI EN 303 413 V1.2.1 (2021-04) standards used ETSI EN 300 330 V2.1.1 (2017-02)

PRODUCT SAFETY Compliance to LVD,

standard used IEC 61010-1/EN 61010-1

PRODUCT STANDARDS

GNSS systems IEC 61108-1

Maritime navigation and radio communication

equipment and systems IEC 61162-1, IEC 60945 IMO regulations MSC.112(73), MSC.113(73), MSC.114(73), MSC.115(73)

UKOOA compliant

Specifications subject to change without any further notice.



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Navigation (hdg)

MGC (optional)

DP (attitude & hdg)