

MRU 5



KONGSBERG



THE IDEAL MARINE MOTION SENSOR

This fifth generation MRU 5 is specially designed for high precision motion measurements in marine application and for users requiring high accuracy roll, pitch and heave measurements.

Typical applications

The MRU 5 is the ideal sensor for motion compensation of multi-beam echo sounders, offshore cranes, hydroacoustic positioning systems and dynamic motion monitoring of roll, pitch and linear accelerations on offshore structures. The MRU 5 provides documented roll and pitch accuracy of 0.02° RMS at a ±5° amplitude. The unit maintains its specified accuracy aboard any surface vessel or subsea vehicle.

Function

The MRU 5 incorporates three highly accurate accelerometers and three high-end Kongsberg Seatex developed Micro-Electro-Mechanical-Structures (MEMS) gyros of type MRG (MRU Rate Gyro). The MRG gyro combines low noise, excellent bias stability and gain accuracy. Very high reliability is achieved by using solid state sensors with no rotational or mechanical wear-out parts.

The unit is delivered with Windows based configuration and data presentation software. In this software vector arms from where the MRU is mounted to center of gravity (CG) and two individually configurable monitoring points (MPs), can be defined. The heave measurements can be output in four different locations (the MRU itself, CG, MP1 and MP2) simultaneously on serial lines or Ethernet port. Typical monitoring point is the transducer head or the crane tip.

Output variables

The MRU 5 outputs roll, pitch and yaw angles and corresponding angular rate vectors. The unit outputs relative (dynamic) heave, surge and sway positions, velocities and accelerations in adjustable frames.

PFreeHeave® Algorithm

The PFreeHeave algorithm uses past measurements to output a correct and phase-free heave from the MRU. PFreeHeave has an advantage in long swell conditions and for applications that can utilize a heave signal that is delayed some minutes, typical seabed mapping applications.

External inputs

The MRU 5 accepts input of external speed and heading information on separate serial lines or Ethernet for improved accuracy in heave, roll and pitch during turns and accelerations. For time synchronization the MRU accepts 1-second time pulse (1PPS) input on a TTL line (XIN) or as RS-232/422 signal.

Digital I/O protocols

For this fifth generation MRU data is available through both Ethernet interface and serial lines enabling easy distribution of MRU data to multiple users on board the vessel. Output protocols for commonly used survey equipment are available on two individually configurable serial lines and Ethernet/UDP.

FEATURES

- 0.02° roll and pitch accuracy
- Outputs on RS-232, RS-422 and Ethernet
- High output data rate (200 Hz)
- Precise heave at long wave periods by use of PFreeHeave® algorithms
- Lever arm compensation to two individually configurable monitoring points
- Meets IHO special order requirements
- Small size, light weight and low power consumption
- No limitation to mounting orientation
- Each MRU delivered with Calibration Certificate
- Selectable communication protocols in the Windows based MRU configuration software
- 2-year warranty



TECHNICAL SPECIFICATIONS

MRU 5

ORIENTATION OUTPUT

| | |
|--|-----------|
| Angular orientation range | ±180° |
| Resolution in all axes | 0.001° |
| Accuracy ¹⁾ , ²⁾ roll, pitch (for a ±5° amplitude) | 0.02° RMS |

GYRO OUTPUT

| | |
|--------------------|--------------|
| Angular rate range | ±149°/s |
| Angular rate noise | 0.025°/s RMS |
| Scale factor error | 0.08 % RMS |

ACCELERATION OUTPUT

| | |
|-------------------------------|----------------------------|
| Acceleration range (all axes) | ±30 m/s ² |
| Acceleration noise | 0.002 m/s ² RMS |
| Acceleration accuracy | 0.01 m/s ² RMS |
| Scale factor error | 0.02% RMS |

HEAVE OUTPUT

| | |
|---|---------------------------------------|
| Output range | ±50 m, adjustable |
| Heave accuracy for 0 to 25 s motion periods (real-time) | 5 cm or 5% whichever is highest (RMS) |
| Heave accuracy for 10 s motion period (real-time) | 1 cm or 3% whichever is highest (RMS) |
| Heave accuracy for 0 to 50 s motion periods (delayed) | 2 cm or 2% whichever is highest (RMS) |
| Heave velocity accuracy | 0,01 m/s RMS |

ELECTRICAL

| | |
|-------------------|--|
| Voltage input | 10 to 36 V DC |
| Power consumption | Max 8 W (typical 7.2 Watts) |
| Serial ports: | |
| Com1 | Bidirectional RS-422 |
| Com2 | Bidirectional RS-422 from junction box, user configurable RS-232, RS-422 |
| Com3 & Com4 | Input only, user configurable RS-232, RS-422 |

| | |
|--------------------------------|-------------------------------|
| Analog channels (junction box) | # 4, ±10 V, 14 bit resolution |
| Ethernet output ports | 5 |
| Ethernet UPD/IP | 10/100 Mbps |
| Data output rate (max) | 200 Hz |
| Timing | < 1 ms |

INPUT FORMATS

NMEA 0183, incl. HDT, HDM, ZDA, GGA, VTG, VHW, VBW or MRU Normal format

DATA OUTPUT PROTOCOLS

| | |
|-----------------------------|---------------|
| - MRU normal | - Sounder |
| - NMEA 0183 proprietary | - EM3000 |
| - Atlas Fansweep | - TSS1 |
| - Seapath binary 23, 25, 26 | - PFreeHeave® |
| - PRDID | - KM binary |

OTHER DATA

| | |
|------------------------------|---------------------------|
| MTBF (computed) | 50000 h |
| MTBF (service history based) | 100000 h |
| Material | Anodised aluminium |
| Connector (MIL. spec.) | Souriau 851-36RG 16-26S50 |

WEIGHTS AND DIMENSIONS

| | |
|------------|----------------------------------|
| Weight | 2.2 kg |
| Dimensions | Ø 105 x 140 mm (4.134" x 5.525") |

ENVIRONMENTAL SPECIFICATIONS

| | |
|-------------------------------|--------------------|
| Operational temperature range | -5 °C to +55 °C |
| Storage temperature range | -25 °C to +70 °C |
| Enclosure protection | IP66 |
| Vibration | IEC 60945/EN 60945 |

ELECTROMAGNETIC COMPATIBILITY

| | |
|--------------------------------------|--------------------|
| Compliance to EMC, immunity/emission | IEC 60945/EN 60945 |
|--------------------------------------|--------------------|

¹⁾ When the MRU is exposed to a combined two-axes sinusoidal angular motion with 10 minutes duration.

²⁾ When the MRU is stationary over a 30-minute period.

Specifications subject to change without any further notice.

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